Current loop transmits ac measurements

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Process-control applications use current loops to send information as an analog signal over long distances with high noise immunity. Using the 3-chip circuit in Fig 1, you can measure alternating current or voltage and transmit the results on a 4- to 20-mA current loop. The circuit accepts a 0- to 10-mV ac rms input and provides a 4- to 20-mA output.

The input signal creates a floating voltage across sensing resistor R_{SENSE} , whose size produces 0- to 10-mV rms from the expected sensed current. This floating voltage is the input to a differential-input, single-ended AD22050 sensor interface (IC₁). IC₁ operates at a gain of approximately 20 and drives the low-impedance (8-k Ω) input (pin 1) of the AD736 rms-to-dc converter (IC₂). This converter's full-scale range is 200 mV rms. IC₂'s output drives IC₃, an AD694 voltage to 4- to 20-mA current-loop interface.

Because of their low power consumption, both IC₁ nd IC₂ can operate from the 10V supplied by IC₃'s reference output at pin 7. IC₃, and hence the entire

circuit, operates from the standard 24V loop supply. Because this circuit operates from a single supply, you must bias IC₂'s common input at ½ of IC₃'s 10V output, or 5V. The voltage divider comprising R_1 and R_2 divides the 10V to 5V. R_2 is in parallel with a 10-k Ω resistor inside IC₃.

IC₃'s internal buffer amplifies the difference between IC₂'s output at pin 6 and the 5V rail. This difference ranges from 0- to 200-mV dc for a 0- to 10-mV rms input and produces a 4- to 20-mA current output from IC₃. R₃ allows you to adjust the circuit's gain. R₄ and R₅ set the gain of IC₃'s internal amplifier to 10. R₅ matches R₄ to prevent offsets due to the internal amplifier's input-bias current. This circuit's accuracy is 1.2% of readings from 20 Hz to 40 Hz and 1% of readings from 40 Hz to 1 kHz. The -3-dB bandwidth is 33 kHz. EDN BBS /DI_SIG #1167

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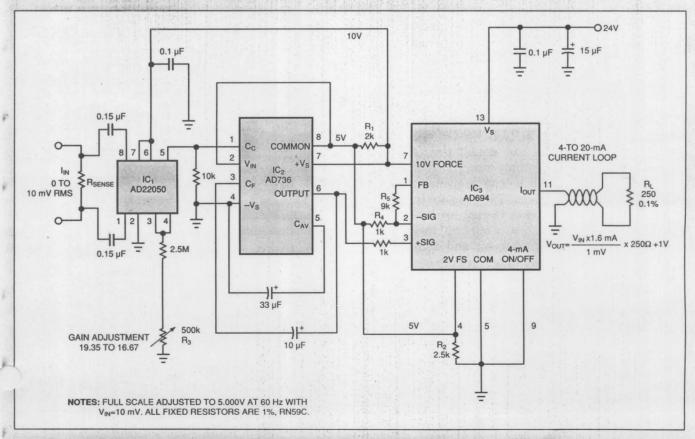


Fig 1—This circuit measures alternating current or voltage and transmits the results on a 4- to 20-mA current loop.